

Plenary Session One

Presentation 2

Driver Assistance Systems – Status Quo and Future Impact on PTI

Preliminary Findings of the vFSS-Group

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2013 CITA Conference

15-17th May, Seville, Spain

CITA 2013 theme “Strategies for Benefiting Roadworthiness ”

Driver Assistance Systems – Status Quo and Future Impact on PTI

Preliminary Findings of the vFSS-Group

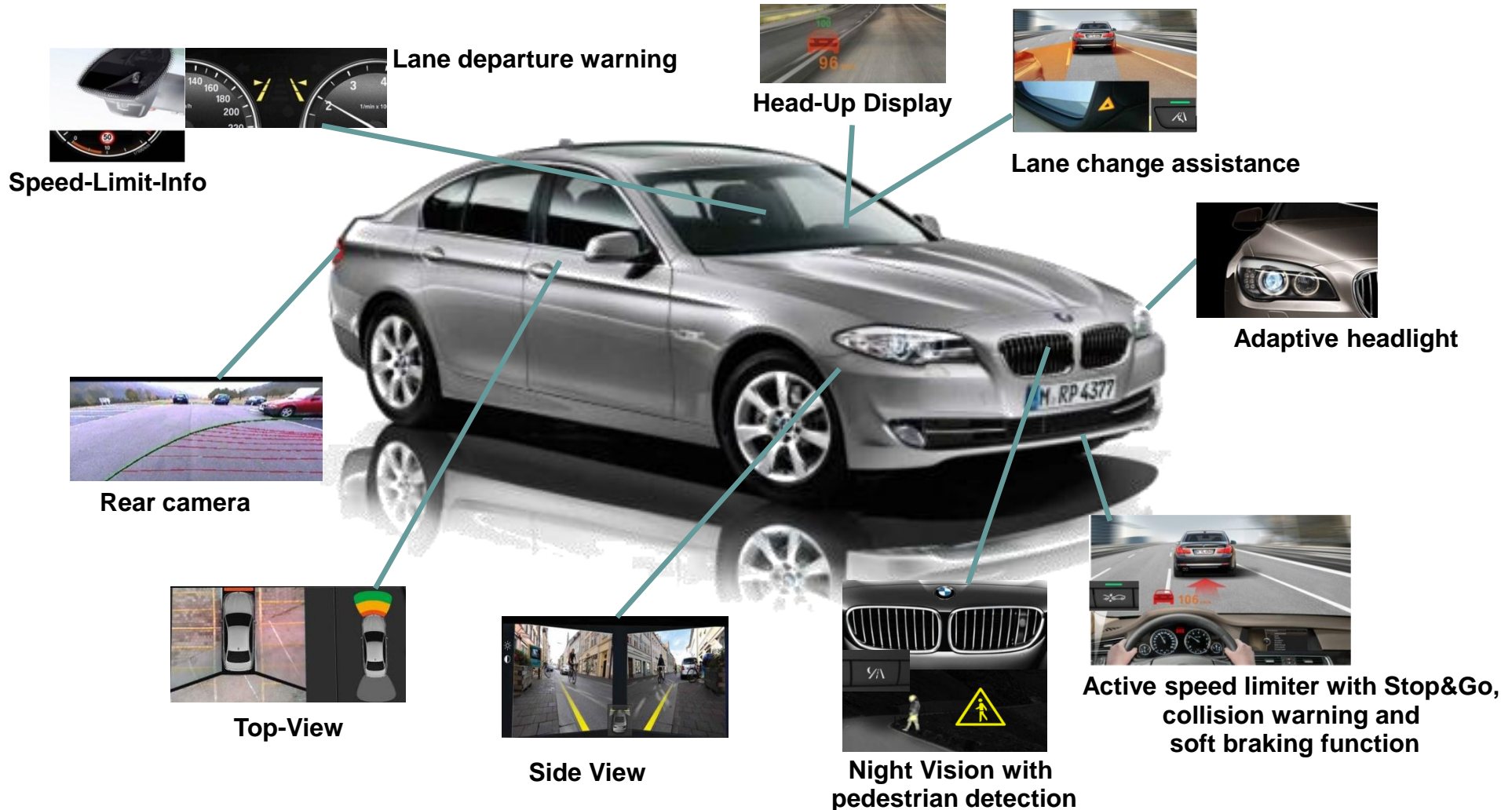
DEKRA Automobil GmbH

Frank Leimbach

Director



State of the art



Nomenclature and Members

vFSS – Adv**v**anced **F**orward-Looking **S**afety **S**ystems

Focus: M1-Vehicles



Background

The aim of the Working Group is the development of test procedures for driver assistance systems (in particular advanced emergency braking systems) in order to ensure a **robust assessment** of such systems.

Focus on **traffic accident priorities** by means of an evaluation of the effectiveness in real world accidents, with the aim of reducing the number of road traffic casualties.

Ensure transparency with respect to legal requirements and consumer protection initiatives, incorporating harmonisation principles and accounting for related trade offs.

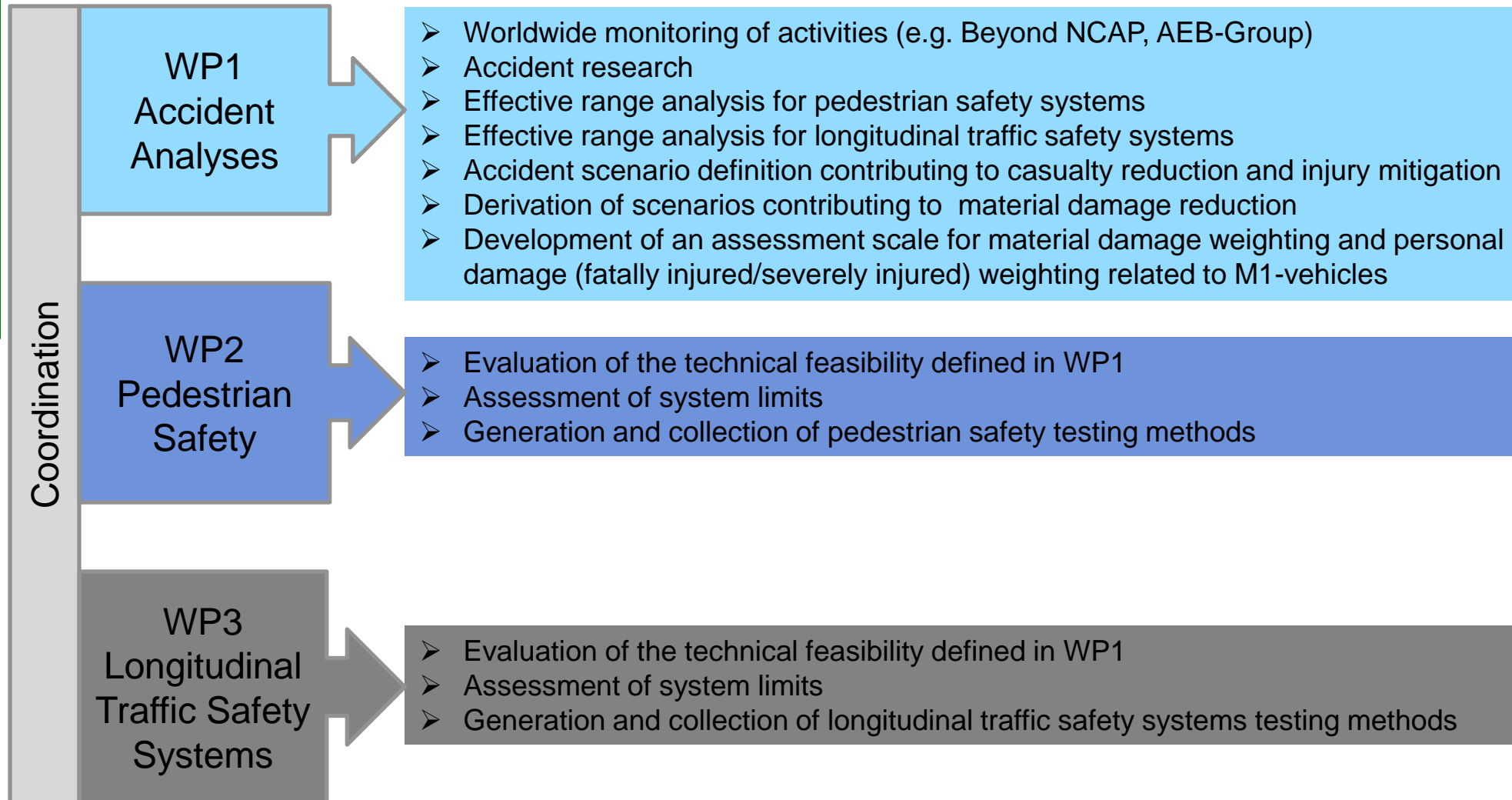
Determination of a **harmonised methodology** for effective evaluation.

Incorporation of conclusions into P-Safe and Euro NCAP working groups in a first step.
Establishment of strategic alliances within other NCAP markets.

3 work packages:



vFSS Group Workpackages



Longitudinal Traffic Safety Systems

WP3 Longitudinal Traffic Safety Systems



Test Procedure and Target Evaluation

WP3 Longitudinal Traffic Safety Systems - Target



Background and History of Test Procedure Development

Overall Focus of vFSS-working group 3 :

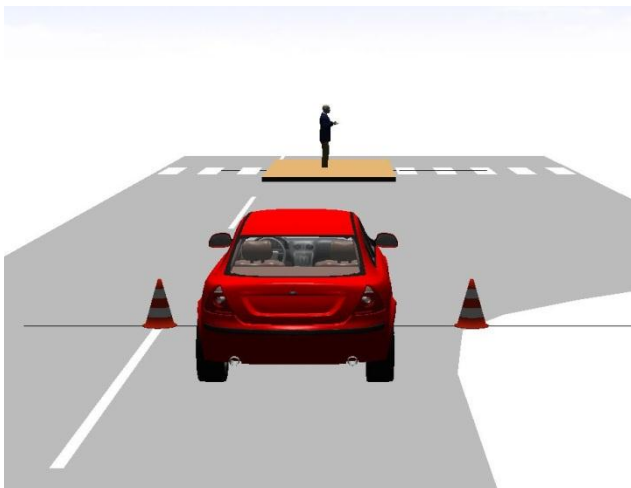
- longitudinal crash scenarios
- Development requirements for crash-targets
- Development of test-procedures for autonomous and adaptive braking systems



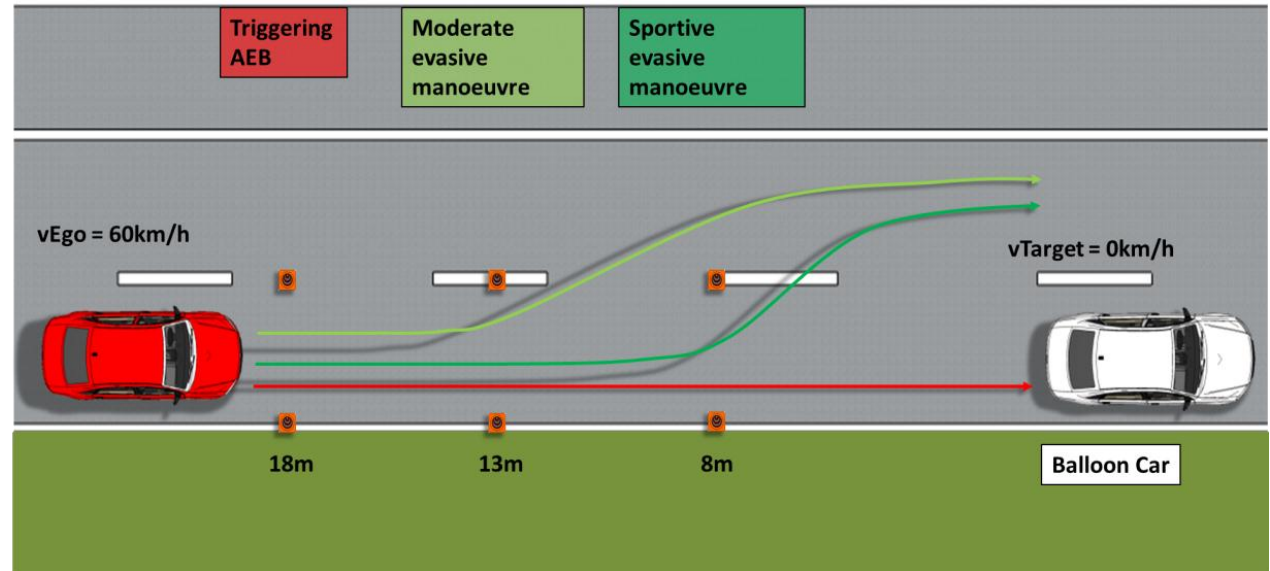
05

Bremsen BMW

Braking or steering

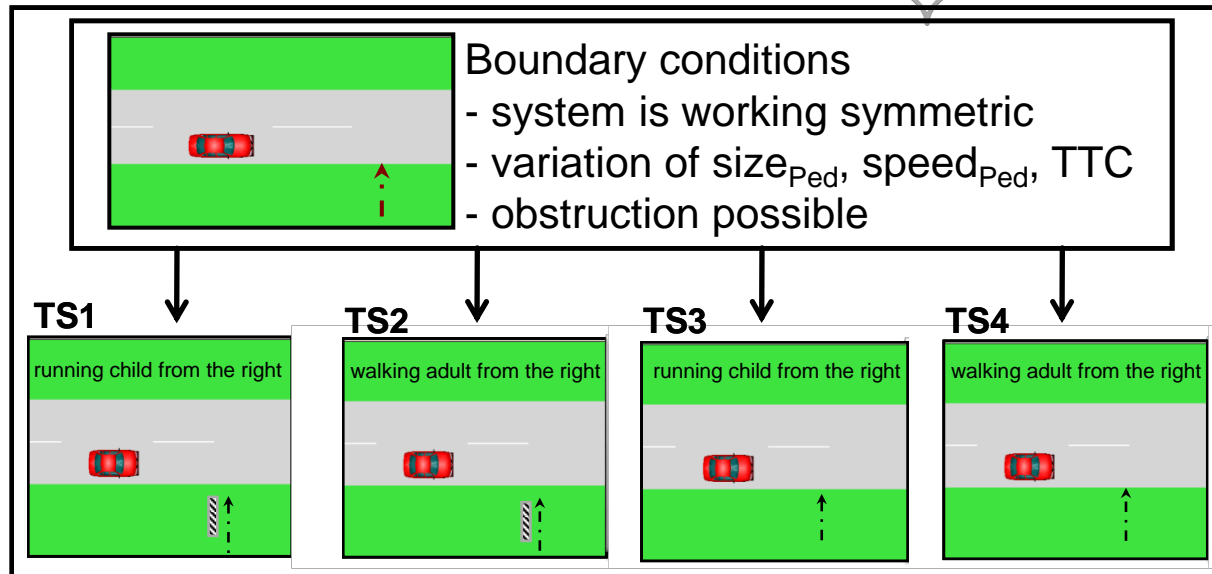
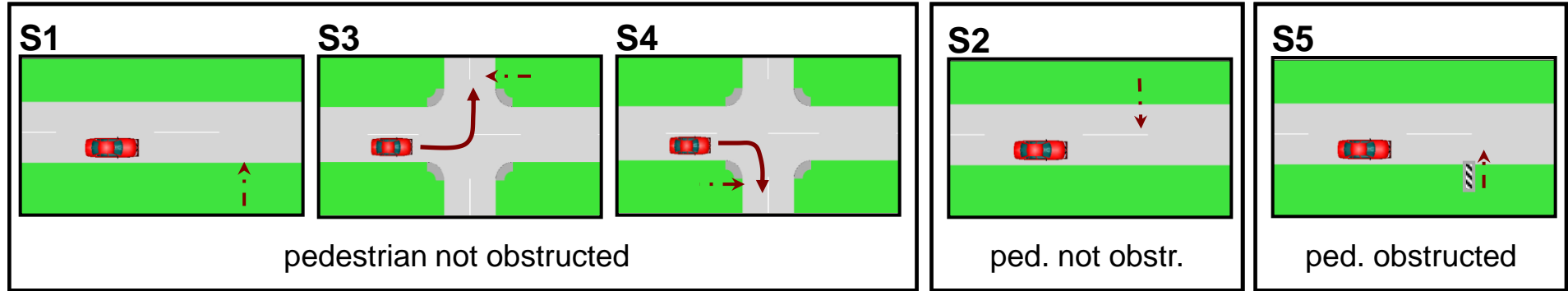


Scenario 1:

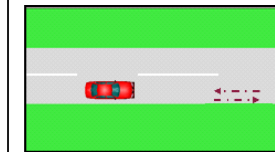


Pedestrian Safety

Transferring accident scenarios to test scenarios



S6 excluded

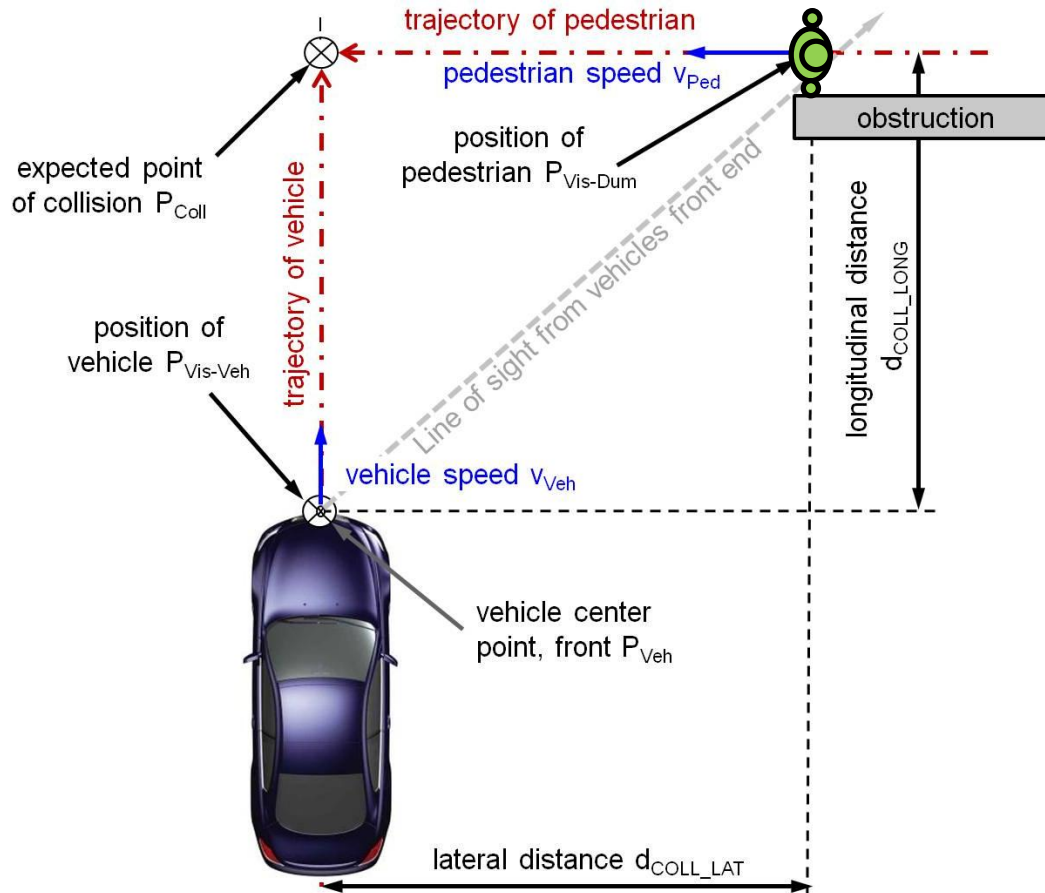


Easy to detect
High speed
($> 70 \text{ km/h}$)

S – Accident Scenario

TS – Test Scenario

Transformation to Laboratory Test



Principle

- moving vehicle
- moving dummy target
- perpendicular moving directions
- continuous velocity measuring for vehicle and dummy target

Relevant values

- vehicle velocity at point of first visibility of the dummy target (P_{Vis_Veh})
- vehicle velocity at the collision point (P_{Coll})
- vehicle's speed reduction is the relevant value to assess the system performance

Testing

- 4 different test scenarios
- 10 test cycles for each scenario

Ideally the tests should be performed contactless to avoid damage of sensor systems

Possible Test Rig

Erprobung

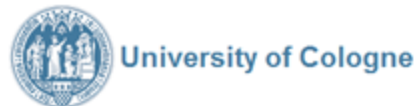
Interlink with EC-Projects



Assessment of Integrated Vehicle Safety Systems
for improved vehicle safety



DAIMLER



TOYOTA



Interlink with EC-Projects





Assessment methodologies
for forward looking Integrated
Pedestrian and further extension
to Cyclist Safety Systems









Memorandum of Cooperation NHTSA-BASt

Signed 26 April 2010



 
MEMORANDUM OF COOPERATION For Motor Vehicle Safety Research between the National Highway Traffic Safety Administration of the Department of Transportation of the United States of America and the Federal Highway Research Institute of the Federal Ministry of Transport, Building and Urban Development of the

<p>The National I of Transportat (Bundesanstalt Urban Develop a Memorandu Transportation Federal Repub Washington, D</p> <p>Recognizing th technology;</p> <p>Recognizing th efficiency, and</p> <p>Desiring to enl motor vehicle out its responsi</p>	<p style="text-align: center;">Section 8 Duration</p> <p>The duration of this MOC is intended to be consistent with the effectiveness of the Agreement, or any extension or amendment thereof. The activities under this Memorandum may commence upon the date of the signatures below of both Participants. This Memorandum may be modified in writing at any time by both Participants and may be terminated upon 60 days written notice by either Participant.</p> <p>Signed in duplicate in English at Washington, D.C. on this <u>26</u> day of April, 2010.</p> <table border="0" style="width: 100%;"><tr><td style="text-align: center;"> _____ Peter Reichelt President Federal Highway Research Institute of the Federal Ministry of Transport, Building and Urban Development of the Federal Republic of Germany</td><td style="text-align: center;"> _____ David Strickland Administrator National Highway Traffic Safety Administration Department of Transportation of the United States of America</td></tr></table>	 _____ Peter Reichelt President Federal Highway Research Institute of the Federal Ministry of Transport, Building and Urban Development of the Federal Republic of Germany	 _____ David Strickland Administrator National Highway Traffic Safety Administration Department of Transportation of the United States of America
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- Safety must be kept on an appropriate level
- Therefore ensure that vehicles on the roads are maintained to a high degree of technical roadworthiness
- Increasingly complex and dynamic functionality of vehicle systems
- Critical safety systems that only operate when the vehicle is in motion such as ESC or AEBs
- Real testing of safety systems within PTI not feasible (time & costs)

- Procedure: VIN specific safety system data delivered by OEM
- Fitment test of safety system
- Functional test based on OBD system data

Thank you very much for your attention



Plaza de España, Seville, Spain